

TECHNICAL REPORT GL-81-6

STRUCTURAL ANALYSIS COMPUTER PROGRAMS FOR RIGID MULTICOMPONENT **PAVEMENT STRUCTURES WITH** DISCONTINUITIES-WESLIQID AND WESLAYER

Report 3

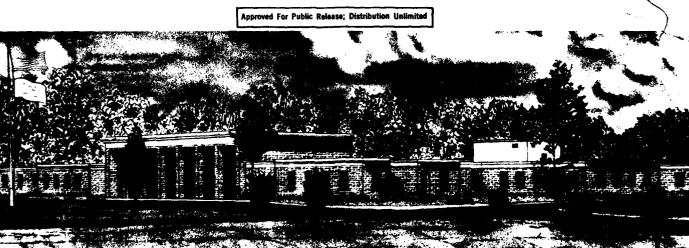
MANUAL FOR THE WESLAYER FINITE ELEMENT PROGRAM

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Geotechnical Laboratory U. S. Army Engineer Waterways Experiment Station P. O. Box 631, Vicksburg, Miss. 39180

May 1981

Report 3 of a Series



Prepared for Office, Chief of Engineers, U. S. Army Washington, D. C. 20314

Under Project No. 4A762719AT40, Work Units 001 and 003



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AUTHOR(s)	8. CONTRACT OR GRANT NUMBER(*)
Yu T./Chou	
9. PERFORMING ORGANIZATION NAME AND ADDRESS	10. PROGRAM ELEMENT, PROJECT, TASK
U. S. Army Engineer Waterways Experiment Station	RDT&E Project No.
Geotechnical Laboratory P. O. Box 631, Vicksburg, Miss. 39180	4A762719AT40 Work Units 00
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Office, Chief of Engineers, U. S. Army	, May 2 81
Washington, D. C. 20314	73. NUMBER OF PAGES
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20. ABSTRACT (Continued).

regions of the pavements. Multiple-wheel loads can be used in the computation and the number of wheels is not limited. Because of large storage space needed and long computer time required to obtain solutions, the program is limited to only a two-slab system.

The nature of the computer program and its program logic are first delineated, followed by a general discussion on the efficient and correct use of the program. An input guide to the computer program is presented with a detailed explanation for each input variable. Example problems with input data and output printouts are presented.

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PREFACE

The study described herein was sponsored by the Office, Chief of Engineers, U. S. Army (OCE), as a part of the Mobility and Weapons Effects Technology RDT&E Project No. 4A762719AT40, Work Unit 001, "Airfield Pavement Design and Parametric Sensitivity Analysis," and Work Unit 003, "Rigid Airfield Pavement Load-Deformation Response Analysis."

This report is Report 3 of a three-report series concerning the computer programs WESLIQID and WESLAYER, which provide for analysis of rigid multicomponent pavements with discontinuities on liquid foundations (WESLIQID) and on linear layered elastic solids (WESLAYER). This report is a user's manual for WESLAYER. Report 1 presented the theoretical background of the programs and numerical results and discussed the capability and logic of the two programs. Report 2 was a user's manual for the WESLIQID program.

The study was conducted by the U. S. Army Engineer Waterways Experiment Station (WES), Geotechnical Laboratory (GL), under the general supervision of Dr. Don C. Banks, Acting Chief, GL; Dr. Paul F. Hadala, Assistant Chief, GL; and Mr. Alfred H. Joseph, Chief, Pavement Systems Division (PSD), GL. Dr. Yu T. Chou, PSD, was in charge of the study and is the author of the report. Professor Y. H. Huang of the University of Kentucky, who originally developed the computer programs, assisted in the study.

COL John L. Cannon, CE, and COL Nelson P. Conover, CE, were Commanders and Directors of the WES during this study and the preparation of this report. Mr. Fred R. Brown was Technical Director.

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CONVERSION FACTORS, U. S. CUSTOMARY TO METRIC (SI) UNITS OF MEASUREMENT

U. S. customary units of measurement used in this report can be converted to metric (SI) units as follows:

Multiply	Ву	To Obtain
Fahrenheit degrees	0.555	Celsius degrees or Kelvins*
feet	0.3048	metres
inches	2.54	centimetres
pounds (force)	4.448222	newtons
<pre>pounds (force) per cubic inch</pre>	0.2714	megapascals per metre
pounds (force) per inch	175.1268	newtons per metre
<pre>pounds (force) per square inch</pre>	6.894757	kilopascals

^{*} To obtain Celsius (C) temperature readings from Fahrenheit (F) readings, use the following formula: C = 0.555 (F - 32). To obtain Kelvin (K) readings, use: K = 0.555 (F - 32) + 273.15.

STRUCTURAL ANALYSIS COMPUTER PROGRAMS FOR RIGID MULTICOMPONENT PAVEMENT STRUCTURES WITH DISCONTINUITIES-WESLIQID AND WESLAYER

MANUAL FOR THE WESLAYER FINITE ELEMENT PROGRAM

PART I: INTRODUCTION

Background

1. The U. S. Army Corps of Engineers (CE) has realized for many years that much of the maintenance of rigid pavements is associated with cracks and joints. Current CE rigid pavement design procedures have certain limitations that were imposed by the state of the art at the particular stage of development. During the development of the procedure, it was necessary to make simplifying assumptions and, in many instances, to ignore the effects of cracks and joints. Since the advent of high-speed computers and the development of the finite element method, a more comprehensive investigation of the state of stress at pavement joints, cracks, and other locations in multicomponent pavement structures than previously possible can now be achieved. Consequently, a better and more reasonable design procedure may be developed for rigid pavements.

Purpose

2. The development of the finite element programs and the analysis of computed results are presented in Report 1 of this series. This report presents a user's manual for a computer program named WESLAYER. The program computes the state of stress in a rigid pavement supported on a layered elastic foundation, as well as in the supporting subgrade soils.

Scope

3. The computer program is described in this report to give users a concise picture of the program without reference to Report 1. The logic of the programming is explained with the illustration of a flowchart. An input guide to the computer program is given, and four example problems are presented to illustrate input procedures for use of the computer program. The outputs of the example problems are explained.

PART II: PROGRAM DESCRIPTION

- 4. This report describes a finite element computer program named WESLAYER programmed for the analysis of concrete pavements subjected to multiple-wheel loads. The program is developed for a subgrade soil represented as a linear layered elastic solid. Any number of layers can be accommodated. Because of the assumption of an elastic soil, vertical force at one nodal point in the subgrade causes vertical movements at all other nodes and vice versa. This behavior is different from that of a liquid foundation (WESLIQID). In the liquid foundation, the vertical force or deflection at one nodal point in the subgrade is not affected by those at other nodes.
- 5. The program determines stresses and displacements in the pavement and in the supporting subgrade soil due to loads and temperature warping. Part of the pavement can be out of contact with the supporting subgrade before applying the load and the temperature gradient, and the program determines the condition of contact at each nodal point after the application of loads and a temperature gradient. Input data of the programs include (a) the property and geometry of the pavement and subgrade soil, (b) the magnitude and distribution of the loads, (c) the temperature gradient, (d) gaps under the pavement at certain nodal points, if any, and (e) joint and crack conditions.
- 6. Multiple-wheel loads can be input and the number of wheels is not limited. Because of the large computer storage space required, the program can handle only two slabs, except for the special option where a four-slab pavement system is loaded symmetrically at the pavement's center. At the joint, the program considers only the shear transfer and assumes the moment transfer to be zero.

PART III: PROGRAM APPROACH

- 7. The storage space required for the program depends on the total number of elements used in the problem. An iteration scheme is used in the program so that the computation is made only for one slab at each time. This scheme results in a great reduction in computer time because the number of equations to be solved each time is reduced to only one slab. Two series of iterations are involved in the program: one is with respect to subgrade contact and the other is with respect to load transfer across the joint.
- 8. In the iteration with respect to subgrade contact, the contact condition at each node, i.e., whether the slab and subgrade are in contact or not, is first assumed, and the iteration with respect to load transfer proceeds until either the convergence criteria (DEL in Item 11 of the input guide, Table 1*) are satisfied or the maximum allowable number of iterations (ICL in Item 10 of Table 1) is reached. At this stage, the resulting contact condition is determined. If some nodes originally assumed in contact are found out of contact or some nodes assumed out of contact are found in contact, the newly found contact condition is assumed, and the process is repeated until the same contact condition is obtained. This can usually be achieved within only a few iterations. The only control by the user is to specify the maximum number of iteration cycles, NCYCLE. If NCYCLE = 1, the contact condition between the slab and subgrade is known a priori, and no iterations are needed.
- 9. In the iteration with respect to load transfer across the joint, the computation is made successively between the left and right slabs. The vertical deflections are used for checking convergence.
- 10. The program carries out the computations (shown in the flowchart, Figure 1) in the following sequence:

^{*} The input guide (Table 1) appears in Part IV, where it is discussed in detail.

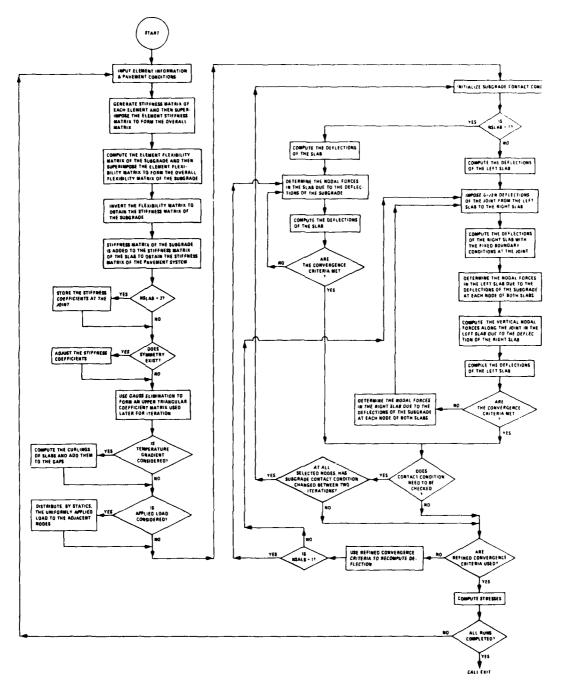


Figure 1. Flowchart for WESLAYER program

- a. Generate stiffness matrix for each element (of the slabs) and then superimpose them to form an overall stiffness matrix.
- <u>b.</u> Compute the element flexibility matrix of the subgrade and then superimpose them to the matrix of the slab to form the overall flexibility matrix.
- <u>c</u>. Invert the flexibility matrix, using the inversion subroutine SMIN, to obtain the stiffness matrix of the subgrade.
- d. The stiffness matrix of the subgrade is added to the stiffness matrix of the slab to cover the stiffness matrix of the pavement system.
- Store the stiffness matrix adjacent to joints for later use.
- <u>f</u>. If it is known that gaps exist under certain nodes in the subgrade soil, the gaps are read into the program to combine them with the computed curls of the slabs due to temperature warping to form the initial subgrade contact condition.
- g. Determine the nodal reactive condition based on the subgrade contact condition.
- h. If externally applied loads are considered, the uniformly applied loads are distributed to the adjacent nodes using statics.
- i. Compute the displacements of the left slab, assuming that there is no shear and moment transfer along the joints, i.e., that slab 1 has four free edges.
- j. Impose deflections along the joint from the left slab to the right slab and compute the displacements of the right slab. This is done with a fixed boundary condition at the joint.
- k. Determine the nodal forces in the left slab due to the deflections of the subgrade at each node in the two slabs. (Note that this process is not needed in the WESLIQID program in that the reactive force at a certain node depends only on the deflection at that node but not elsewhere.)
- 1. Compute the vertical nodal forces along the joint in the left slab due to the deflection of the right slab.
- m. Compute the deflections of the left slab again. The values are compared with those computed in the previous iterative cycle. If the convergence criteria are not met, the nodal forces in the right slab due to the deflections of the subgrade at each node of both slabs are

- computed and the process between steps j and m are repeated until the deflections at the preselected nodes converge to a specified tolerance.
- n. Once a convergent solution has been obtained or the maximum allowable number of iterative cycles has been reached (ICL in Item 10 of Table 1), the signs of the deflections at each node are compared with those of the initial (or the previous) subgrade contact condition. A change of sign at any node indicates that the contact condition at these nodes has changed. Based on the renewed subgrade contact condition, the computational process from steps a to m is repeated. The iteration process stops when either the contact condition ceases to change or the maximum allowable number of iterations (NCYCLE at Item 4 of Table 1) has been reached. Note that when the subgrade contact condition is changed, the subgrade stiffness is also changed.
- o. Once the subgrade contact condition is unchanged, the computational process from steps j through m is repeated once more with a refined convergence criterion. The controlling variables in the program are ICLF in Item 10 and DELF in Item 11 of Table 1.
- p. The stresses at selected nodal points are computed based on the curvature of the deflected slab, i.e., the nodal displacements.
- q. Compute stresses and deflections in the subgrade if so desired.
- r. Note for a single slab, i.e., NSLAB = 1, steps j to m are skipped if a full bandwidth NB is used.
- ll. For a single slab, steps j and l are neglected; i.e., the left slab is the only slab.
- 12. In computing the subgrade reactive forces at each nodal point, Boussinesq's homogeneous analysis and the layered elastic theory are used to formulate the flexibility matrix for single-layer and multilayer subgrade soil, respectively. In the multilayer case, the layered elastic theory is not used directly at every nodal point in order to save computer time; rather, the theory is used to compute the deflections at 21 different offset points, and interpolation subroutines are used to interpolate the deflections at node j due to the load at node i.

PART IV: OPERATION OF THE PROGRAM

General Discussion

- 13. As with other numerical procedures for solving structural problems, the accuracy of the finite element method depends greatly on the correct use of the technique. While the computational cost and storage space increase drastically with an increased number of elements, the program does require a reasonable number of elements. The element size should be smaller near the loads and joints where stresses are transferred to another slab. In some cases, the minimum number of elements for a particular problem has to be determined by a trial-anderror procedure. It was found that an insufficient number of elements can cause the solution to diverge; this is particularly true when temperature warping is considered and gaps exist under the pavement. Also, users should be aware that the aspect ratio of an element, defined as the ratio of the larger dimension to the smaller dimension of a rectangular element, should not exceed four or five to one. It is always good practice for the beginning user of this program to familiarize himself with the program by using different numbers of elements for a particular problem and then comparing the results.
- 14. The input guide for the program is presented later in this Part. Special features in the correct and efficient use of the program are presented and discussed in the following paragraphs.

 Dimension requirements
- 15. The method developed in this program can be applied only to two slabs. The dimensions of C * and G vary with the number of elements and the half bandwith and can be computed as

$$\sum_{1}^{\text{NSLAB}} \text{(total nodal points)} \times 3 \times \text{NB}$$
 (la)

^{*} Symbols used in the WESLAYER program are defined in the input guide (Table 1).

where NB is the half bandwidth and is equal to $(NY + 2) \times 2$. The symbol NY represents the number of nodes in the Y-direction. When the dimensions of C and G are changed in the main program, they should also be changed in the corresponding subroutines.

- 16. The dimensions of many important variables in the present program are limited and should be increased if the number of elements is increased. The limited dimensions of variables are presented as follows:
 - a. The maximum nodal number (NO23) is 70 and the maximum number of elements is 60. To increase element size, the dimensions of the variables DF, PPF, PF, CURL, FO, AB, NCC, REA, and REACT should be increased in accordance with the total number of nodes NO23; and the dimension of the variable DEF is to be increased as the total number of elements.
 - b. The maximum numbers of NMCF and NPRINT are 35 and 30, respectively. When the value of NPRINT is changed, the dimension of the variable NP should be changed accordingly.
 - c. The dimensions of H (so is A), F, and CO are determined by the formulas

 $N023 \times (N023 + 1)/2$; 3 × N023; and 3 × NB × NY

respectively. Variable A is in the subroutine SMIN .

- d. The maximum number of nodes that have gaps under the pavement is 30. When this is increased, the dimensions of the variables NG and GAP should also be increased.
- e. The maximum number of loads is controlled by the variable NL. When the dimension of NL is increased, the dimensions of XDA and YDA should also be increased accordingly.
- f. The maximum number of layers is 5. If more layers are desired, the dimensions of many variables in the common block RMCOY should be changed.

Element and node numbering system

17. Beginning from the left slab and ending at the right slab,

the nodes and elements are numbered consecutively from bottom to top and then from left to right.

Symmetries

- 18. The application of the finite element method for analyzing rigid pavements involves solving a large set of simultaneous equations. However, because of symmetry, the number of simultaneous equations could be greatly reduced by considering only one-quarter or one-half of the slab. The symmetry is with respect to the load, the pavement geometry and property, the finite element grid layout, and the load transfer device along the joint. Users are strongly urged to take advantage of the symmetry option provided by the program to arrange the loadings in such a way that the problem becomes symmetrical. Coded data input for symmetrical example problems are presented in Part V. It should be pointed out that symmetry should not be placed at a joint.
- 19. When the effects due to temperature and loadings are considered separately, the computed results due to temperature alone are expected to be symmetrical with respect to the pavement geometry. For instance, the stresses and deflections are the same at the four corner nodes in a square slab subjected to a temperature warping. This may not be the case, however, if the finite element grid lines are not divided symmetrically. In practical cases, smaller elements can be used around the applied loads, which may result in a nonsymmetrical finite element grid pattern. If this is the case, the computed results due to temperature alone may not be symmetrical as they should be and consequently may affect to a certain extent the final results when the temperature effect is combined with that of the load. The error in most cases is insignificant because the load effect usually outshadows the temperature effect. Nevertheless, users should be aware of this possible discrepancy.
- 20. In Figure 4 of Report 2 of this series, the loads are placed at the pavement's center next to the joint. Smaller elements are used around the loads and larger elements are used elsewhere. Although the finite element pattern is symmetrical in the up-and-down direction with

respect to the pavement's center line and symmetrical in the left-and-right direction of the two-slab pavement with respect to the joint, the size of each element is not identical. Consequently, if there is no moment transfer along the joint, the computed results due to the temperature effect at nodes 1 and 57 are not equal, as they theoretically should be. Consequently, the final computed results are not strictly correct. However, the error is believed to be insignificant when the effect of applied loads is combined.

Half bandwidth

21. The definition of the half bandwidth of a matrix can be found in any structures book. The size of the half bandwidth directly influences the size of the storage space. A proper nodal numbering system may reduce the size of the half bandwidth. This is illustrated in the two different numbering systems shown in Figure 6 of Report 2 of this series. Both slabs in Figures 6a and 6b have 20 nodes and 12 elements, but the half bandwidth for the arrangement shown in Figure 6a is $(4 + 2) \times 3 = 18$) and that of Figure 6b is $(5 + 2) \times 3 = 21$. The rule of thumb is to arrange the finite element grid with the side having fewer nodes in the vertical direction.

Weight of the concrete slab

- 22. In the classical Westergaard solution, the weight of the slab is not considered in the computation. The consideration of the weight of the slab is an option in this computer program. When temperature and loads are not considered and the subgrade is uniform and in full contact with the slab, the weight of the slab only causes the slab to settle uniformly and induces no bending in the slab. Consequently, stresses are not induced in the slab. In some cases, the consideration of the weight of the slab is mandatory, as discussed below.
- 23. The major difference in procedure between full and partial contact between the slab and the subgrade is that it is not necessary to consider the weight of the slab in the case of full contact, but the weight of the slab must be considered in the case of partial contact.
- 24. When problems involve only temperature warping (no externally applied forces), the weight of the slab must be considered to

avoid the possible divergence of the solution. This is particularly true when gaps exist under some of the nodes. For the case of partial contact, the weight of the slab must be considered even when temperature is not considered.

Selected points of stress computations

25. While the displacements are computed automatically for every nodal point, the stresses are computed only on request. The stress matrix is used each time when the stresses at a nodal point are computed. Some computer time can be saved if the stresses at only a few selected nodes are computed.

Temperature considerations

- 26. When temperature is considered, the dimensions of the two slabs must be identical.
- 27. The computed initial curlings are independent of the arrangement of the finite element grid pattern. The amount of initial curling at each node is computed by Equation 10b in Report 1 of this series. The only variable in Equation 10b is the distance R between the center of each slab to the node where the curling is computed.

Correctness and divergence of the obtained solution

- 28. Users of the computer program should always be scrupulous with the results computed. The stresses and deflections could be computed and tabulated, but the values may not be meaningful. Certain features in the program deserve special attention and are explained in the following paragraphs.
- 29. Number of iterations. When the number of iteration IC has reached the maximum allowable number of iteration ICL and ICLF (Item 10 of Table 1), the solution has not converged. The problem should be recomputed with larger values of ICLF (and also ICL in certain cases). However, it may be wise at this stage to see whether the solution obtained is good enough for engineering purposes. In some cases, a solution may not be obtainable if the convergence criterion is too strict. The same reasoning can be used to check the number of iteration NIC for subgrade contact against the maximum allowable

number of iteration NCYCLE. The value of ICL is not as critical as the value of ICLF; however, a large difference between the actual value of IC (printed in the output) and the specified ICL is not recommended.

- 30. Reduction of relaxation factor RFJ. If convergent results cannot be obtained, the program reduces the factor automatically. A value for the relaxation factor that is too small results in a shear transfer that is too small across the joint during each iteration; consequently, the computed results could be erroneous because the convergence of the solution is artificially enforced.
- 31. <u>Symmetries</u>. When symmetry in a given direction is used and the deflections and stresses across a certain joint are supposed to be equal, the efficiency of load transfer across the joint should be input only as 100 percent. Otherwise, erroneous results will be computed.
- 32. Computed stresses and deflections. The solutions obtained from the finite element application are by no means completely correct; they are merely close, acceptable approximations. The correctness of the computed larger values is more important. The smaller values computed at insignificant locations of the pavement, such as at placed far away from the load, are of no significance in engineering problems.

Input Guide

33. The input guide for the program is given in Table 1, with detailed explanations of each entry presented as follows:

a. Item 1: Number of Runs Card (15).

Notes	Columns	Variables	Entry
(1)	1-5	NRUN	Number of runs to be computed

NOTES:

(1) The number of runs is first specified at the onset of computations. The nature of the problems in each individual run is generally different. However, results of one run can be used in the next run immediately followed by the input NREAD or NREAD1. They are explained in Item 6.

Table 1. Input Guide for WESLAYER -- Slabs on Layered Elastic Solids

GENERAL PURPOSE DATA FORM

REQUESTED BY	PREPARED 8Y	CHECKED BY	PAGE
10 11 12 13 14 15 16 17 16 19	20 21 22 23, 24 28, 28 27 28, 28 27 38, 28 3 2 3 3 3 3 3 3 4 18 36 3 18 38 30 6 42 42 42 42 42 44 42 44	en (+) en en en es	11 62 62 64 65 66 67 66 67 66 70 71 72 73 74 75 75 77 78 79 00
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			Temperatura 1901 1906 1907 1907 1907 1907 1908 1908 1908 1908 1908 1908 1908 1908

. Item 2: Identification Card (12A6)			
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		. 4.4.4.4.4.4.1.4.1.4.1	
. Item 3: Data Card (1215)			
61 9, 51 9	19 19 20 12 12 12 12 12 12 12 12 12 12 12 12 12	OB 64 88 48 89 85 95 85 25 15 05 80 80	81 62 63 64 65 66 67 66 66 70 71 72 73 76 75 76 77 78 79
-	I Y.M. I I X.M.S. P.R.S. N.S. X.M. WOY	P.R.S. N.S.Y.M. MOTOON . MSTORE . MTUNCE .	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1

Item 4: . Data, Card (615)	Item 45. Data Card (615)	7-7-7-7-7-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1	
•			######################################
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		. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1.	THE PERSON AND THE PE
			<u> </u>
Item 5: Stresses Print Card (1615)		. 4. 4. 4. 1 1 1 1 4. 4. 4.	

"ub(t)" 'ub(s)" ub(s)" 'ub(h)"			<u> </u>
		3	21 27 27 27 27 27 27 27 27 27 27 27 27 27
. commune the input motiv the number	NFRIN (Item 4) 18 satisfied.		

(Continued)

(Sheet 1 of 5)

Table 1 (Continued)

GENERAL PURPOSE DATA FORM

Recuesions 1 page 2, 200 page Married Properties Card (1970) 1 1 1 1 1 1 1 1 1	V(2) V(2) E(3) E(3) V(3) V(3) V(3) V(2) V(2)	he marber of H (m) H	ED 0V V(3) V(3) De pumber of De pumber o	
Item 6: Subgrade Marerial Properties Card (8710.2) V[2] V	E(3) 1 (1) (1) (1) (1) (1) (1) (1) (1) (1)	V(3) V(3) V(3) V(3) V(3) V(3) V(3) V(3)		
Item 6: Subgrade Material Properties Card (8710.2) V/2 V/2 E(2) V/2 V/2 E(2) V/2 V/2 E(2) V/2 E(2) V/2 V/2 E(2) V/2 E(2) V/2 E(2) V/2 E(2) V/2 E(2) E(2) V/2 E(2) E(2	ed. Skip to Item 8 if the	~ -		## (2 1 1 1 1 1 1 1 1 1
E(HIA) Continue the input until the number of HIA (New 4) is satisfied a layered spartic subgrade HIA "1. Invered spartic subgrade HIA "1. Invered spartic subgrade HIA "1. Item 7: Subgrade invert Thickpess Card (1879.2) Continue the input until the number of NN is satisfied, where continue the input until the number of NN is satisfied, where it is a set of the number of layered elastic subgrade is 1. Card 1: X-coordinates Card 2: X-coordinates Card 2: Y-coordinates Card 2: Y-coordinates	ed. Skip to Item 8 if the	-		1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
E(MTA) Continue the input until the number of MTA (New 4) is satisfied a layered elastic subgrade MTA " 1 Layered elastic subgrade MTA " 1 Layered elastic subgrade MTA " 1 Continue the input until the number of NN is satisfied, where a layer of layered elastic subgrade is 1. Card in X occordinates Card in X coordinates Card 2: Y-coordinates Card 2: Y-coordinates	ed. Skip to Item 8 if the			1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
Continue the input until the number of Ela (Tem 4) is satisfied livered elastic subgrade HA = 1. Livered elastic subgrade HA = 1. Livered elastic subgrade HA = 1. Continue the input until the number of NN is satisfied, where z = 1 the number of layered elastic subgrade is 1. Zer 8: Sodal Points Coordinates Cards (8199.2) Lien 8: Sodal Points Coordinates Cards (8190.2) Card 1: X-coordinates Card 2: Y-coordinates Card 2: Y-coordinates	NN = NIA (Item 1). Skip			1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
Layered elastic subgrade MA = 1	NN = NIA (Item 1). Skip	1 -		1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
	NN = NIA (Item 1). Skip			## (2 1 1 1 1 1 1 1 1 1
Hi(p) Hi(p	HN = NIA (Item 1). Skip	•	α (a) (a) (a) (a) (b) (a) (b) (b) (c) (c) (c) (c) (c) (c) (c) (c) (c) (c	111111111111111111111111111111111111111
Hi(p) Hi(p	HN = NIA (Item 1). Skip		0.00 (a) (a) (a) (b) (b) (c) (c) (c) (c) (c) (c) (c) (c) (c) (c	SCR CE PE
HI(3), HI(2), HI(2), HI(3), HI(3), HI(4), HI(3), HI(4), HI	HN = NIA (Item 1). Skip	1 1	42 64 64 64 64 64 64 64 64 64 64 64 64 64	# R C
Hi(1), Hi(2), Hi(2), Hi(3), Hi(3), Hi(4), Continue the input until the number of NN is satisfied, where is if the number of layered elastic subgrade is 1. [Igen 8: Polal Points Googdingtes Cards (879.5), Card 1: X-coordinates [X(1,1), X(1,2), X(1,2), X(1,2), X(1,3), X(1,3), X(1,1), X(1,2), X	NN = NIA (Item 1). SAID		(0.2 (0.2	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2
Continue the input until the number of NN is satisfied, where is a set of the number of layered elastic subgrade is l. Item 8: Bolal Points Gooddinates Cards (8710.5)	NN = NLA (Item 4). Skip	• - 1 - 1	1.62 63 64 65 66 65 66 69 70 7	8C 8
		-	0.00 00 00 00 00 00 00 00 00 00 00 00 00	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2
		*********	. 1 4 6 4 4 4 6 4 1	7717111
Item 8: Bodal Points Condinates Cards (879.5)				
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Li X(12) Li X(12) Li X(12) Li Li X(17) Li Li X(17) Li Li X(17) Li Li X(17)	_			*********
Card 2: Y-coordinates	' ' x{s^1} ' ' ' x {s^2} ' ' ' ' ' ' ' x {s^2} ' ' ' ' ' ' ' x {s^3} ' ' ' ' ' ' ' x {s^3} ' ' ' ' ' ' ' x {s^3} ' ' ' ' ' ' ' ' x {s^3} ' ' ' ' ' ' ' ' ' x {s^3} ' ' ' ' ' ' ' ' ' x {s^3} ' ' ' ' ' ' ' ' ' ' ' ' ' ' ' ' ' '	, ,x{2,2}	, , , x{2 ₁ 3}, , ,	7 7 7 1 1 7 1 2
Card 2: 1-coordinates	***************************************			

1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.	(<u></u>		CITITION OF STREET	
1				
Item 9: Subgrade Contact Card (1618)	***************************************			1177111
-				
NZ(1) NZ(2) NZ(3) NZ(4)	200)			
+ + + + + + + + + + + + + + + + + + +	*			+ + + + + + + + + + + + + + + + + + + +
' a Continue the input until the number of NOTCON (Item 3) is satisfied. Skip to the next table if NOTCON = 0 .	ikip to the next table if		25 80 61 52 63 66 65 65 65 67 68 69 70 7	المامينية المامينية

(Continued)

(Sheet 2 of 5)

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Table 1 (Continued)

GENERAL PURPOSE DATA FORM

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REQUESTED BY PREPARED BY	CHECKED BY	PAGE	OF.
2 3 4 5 6 7 0 9 10 11 12 13 14 (15 14 15 14 15 15 15 15 15 15 15 15 15 15 15 15 15	48 48 50 51 52 53 54 55 56 57 58 88	40 61 62 63 64 65 66 67 66 69 70	70 71 72 72 74 75 76 77 78 79 80
Item 10; Data Card (612)	ICHOR A. I. A.		4 2 5 2 5 2 5 3 3
1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1			
> -		**************************************	************
Item 12: Concentrated Forces and Moments Card [4[15,25,F]0.2]]			
(†)-1-1-3.	13 setieffed.		
2 - 2 - 3 - 5 - 6 - 9 - 9 - 9 - 9 - 9 - 9 - 9 - 9 - 9	17 48 40 50 51 52 53 54 55 56 57 56 59 60	61 62 63 64 65 66 67 68 70	71 72 73 74 75 76 77 78 78
Skip to the next item if NOCP = 0	1 1 4 4 4 1 1 4 4 4 4 4 4 4 4 4 4 4 4 4	****	******
Then 33: Check Convergence Card (1615)	**************************************	·	***********
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the next item if 1738 % 0	• • •		
(E CAL SET		-	20 21 22 23 24 25 26 27 38 28

(Sheet 3 of 5)

(Continued)

Table 1 (Continued)

GENERAL PURPOSE DATA FORM

	PAGE OF	90 10 10 10 10 10 10 10 10 10 1
		11. 12. 12. 12. 12. 12. 12. 12. 12. 12.
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Card 2: Gaps (8F10.5)	(1) (1) (1) (1) (1) (1) (1) (1) (1) (1)	8 L R R R R R R R R R R R R R R R R R R
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Item 16: Total Uniformly Applied Load Card (FI2.2)		27 27 27 24 25 74 27 27 27 27 29
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	****************	4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4
	1444-4454444444	T T T T T T T T T T T T T T T T T T T
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05. 60 Eta Cr Seb 20 Ab Cr Ca Ca Ca Ca Ca Ca St St Dt Ct .	1 525) 194 55 54 57 58 59 60 61 62 63 64 65 64 67 68 67 68 67 68 67 68 67 68 67 68 68	69 47 87 77 36 75 74 95 67 77 17 07 80
WES """ 1233 FOTOGES SERVE EN MEDICE FRANCIES		

(Continued)

(Sheet μ of 5)

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Table 1 (Concluded)

GENERAL PURPOSE DATA FORM

REQUESTED BY	CHECKED BY	PAGE	90
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Item 17: Loading Cards		4 4 4 1 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	*********
Card 1: Loading Elements (1615)	session to the session of the session of the	,,,,,,,,,,,,	*********
L(1) NL(2) NL(3) NL(4) NL(4) NL(1)			
Continue the input until the number of MLOAD (ltem 10) 18 B	BACIBILEA.		
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XDA(T.1) XDA(I.2) YDA(I.1) YDA	XDA(1.2) YDA(1.2) YDA(1.2)		
11 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	JAD in Item 10, continue to next data card	using	
same format. Skip Item 16 if NLOAD = 0.	olicem 16 if Nichall Control of the		
2 3 6 5 6 7 6 9 10 11 12 13 14 15 15 15 12 22 22 22 22 23 25 25 25 25 25 25 25 25 25 25 25 25 25	14 C. 15 C.	57 58:59 60 61 62 63 66 65 66 67	66 66 70 72 73 74 75 76 75 77 77 77
Item 18: Subgrade Stress Card			4.4 4 4 4 4 4 4 1 1

Lara I. Number of Computations	(21,0)	1 1 1 1 1 1 1 1 1 1 1 1	
MES			**********
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-			
Card 3: Offiset card (8F10.5)			(arroy
1 A. C.		1.1.4 () YK (.w.K	J I J.K. (M. K.)
SKIP I TEM 18 IF NOMP = 0	ACMANA TO THE PROPERTY OF THE		
	2 25 25 25 25 25 25 27 27 27 28 28 28 28 28 28 28 28 28 28 28 28 28		

b. Item 2: Identification Card (A80).

Notes	Columns	Variables	Entry
(1)	1-80	TITLE(12A6)	Enter the heading in- formation to be printed with the output

NOTES:

(1) Begin each new problem with a new heading card.

c. Item 3: Data Card (1615).

Notes (1)	Columns	Variables	Ent mr
(1)		Variables	Entry
(1)	1-5	NSLAB	Number of slabs in the model
	6-10	PR	Poisson's ratio of the concrete, generally use 0.15
	11-15	T	Thickness of the concrete
	16-25	MY	Young's modulus of the concrete
(2)	26-35	YMS	Young's modulus of the subgrade
(2)	36-40	PRS	Poisson's ratio of the subgrade
(3)	41-45	NSYM	Condition of symmetry
(4)	46-50	NOTCON	Total number of nodes at which reactive pressure is initially set at zero
(5)	51-55	NSTORE	Options for thermal stress and thermal deflections:
			EQ.0 The values determined from the previous problem are not used, or it is a new problem
			EQ.1 The values deter- mined from the previous problem are used
	(2) (3) (4)	11-15 16-25 (2) 26-35 (2) 36-40 (3) 41-45 (4) 46-50	11-15 T 16-25 YM (2) 26-35 YMS (2) 36-40 PRS (3) 41-45 NSYM (4) 46-50 NOTCON

Notes	Columns	Variables	Entry
	56-60	NPUNCH	Option for punching values of thermal stresses and deflections on cards:
			EQ.O No
			EQ.1 Yes
(6)	61 - 65	NB	Half bandwidth of the matrix
	66-70	LTR	Option for computing load transfer along the joint:
			EQ.O Efficiency of shear transfer is read in
			EQ.1 Dowel information is read in

NOTES:

- (1) The maximum number of slabs is 2.
- (2) When the number of NLA is 1, i.e., the subgrade is modeled as a linear elastic solid, YMS and PRS can be any number.
- (3) Assign 1 when no symmetry exists, 2 when symmetric with respect to the Y-axis, 3 when symmetric with respect to the X-axis, 4 when symmetric with respect to both the X- and Y-axes, and 5 for four slabs symmatrically loaded. When subgrade stresses and deflections are computed, symmetry should be used with caution. When either NSX or NSY is not zero, the total number of nodal reactive forces is reduced to one-half, and when both NSX and NSY are not zero, the total number of nodal reactive forces is reduced to one-quarter. Users are urged to distinguish between a four-slab pavement symmetrically loaded (assign 5 for NSYM for this case) and a single slab symmetrically loaded (assign 4 for this case). In the former case, the slabs are divided by joints and the shear transfer across the joints can be assumed either as 100 percent or as by dowel bars. The assumption of shear transfer less than 100 percent is meaningless because of the symmetrical loading. The subgrade reactive force at a node along a neutral axis is only one-half of the nodal force at the node when symmetry is not used. Symmetry should not be used at nodes along a joint.
- (4) If the subgrade soil at certain nodal points is known

to be not in contact with the pavement due to pumping or plastic deformation, the subgrade reactive pressure at these nodes can be initially set at 0 to obtain speeding convergence. If NCYCLE = 1 (NCYCLE is listed in Item 4), these nodes will never be in contact. If NCYCLE > 1, these nodes may or may not be in contact, depending on calculated results.

- (5) In pavement design, engineers are interested in stresses induced by the applied load and the temperature warping. In pavement research, however, engineers tend to measure only stresses due to the applied load because thermal stresses are difficult to measure. To compute stresses and deflections by the load alone, two separate but consecutive runs have to be conducted. The first run computes the thermal stresses alone. This is done by setting NSTORE = 0 , NWT = 1, NTEMP = 1, NGAP > 1 (if this is the case), NOTCON > 0 (if this is the case), and NLOAD = 0 in the first run. In the second run, the stresses induced by the applied load and the temperature warping are computed by setting NSTORE = 1 , NWT = 1 , NTEMP = 1 , NGAP > 1 (if this is the case), NOTCON > 0 (if this is the case), and NLOAD equal to the actual number of loads. The differences between those values computed in the first and second runs are the stresses and deflections due to the applied load along. Note that when temperature is considered, the slab and the subgrade may be in partial contact, the principle of superposition may no longer be held true (see paragraph 47, Report 1 of this series). It should also be pointed out that in the case of the first and second runs discussed above, the measured gaps that are input should not include the gaps due to the temperature warping because they are to be computed.
- (6) The half bandwidth NB should be equal to or greater than $(NY+2)\times 3$, where NY is the number of nodes in the Y-direction. It was found that when the number of equations is large while the half bandwidth is small, the displacements may not converge, and a larger bandwidth should be used. For NSLAB = 1, the solution can be obtained without iteration if a full bandwidth NB is used.

d. Item 4: Data Card (615).

Notes	Columns	Variables	Entry
	1-5	NX1	Number of nodes along the X-axis in slab 1
(1)	6-10	NX5	Number of nodes along the X-axis in slab 2
	11-15	NY	Number of nodes along the Y-axis

Notes	Columns	Variables	Entry
	16-20	NCYCLE	Maximum number of cycles for checking subgrade contact, generally use 10 or more
(2)	21-25	NPRINT	Number of nodes at which stresses and deflections are to be printed
	26-30	NLA	Number of layers in the subgrade
	31-35	NCOMP	OPTIONS for computing stresses and deflections in the subgrade:
			FQ.O No
			EQ.1 Yes

NOTES:

- (1) NX2 = 0 if NSLAB = 1.
- (2) The deflections at each node are computed in the program but the stresses at any node are computed only on request.
- e. Item 5: Stresses Print Card (1615). (1)

Notes	Columns	<u>Variables</u>	Entry
(2)	1-5	NP(I)	Nodal number whose stresses are to be printed

NOTES:

- (1) Deflections are printed for all nodal points.
- (2) Continue the input until the number of NPRINT (Item 4) is satisfied. Continue to next data card if NPRINT is greater than 16.
- f. Item 6: Subgrade Material Properties Card (8F10.2).

Note: Skip Item 6 is NLA = 1.

	-		
Notes	Columns	<u>Variables</u>	Entry
	1-10	E(1)	Young's modulus in layer
	11-20	V(1)	Poisson's ratio in layer
	21-30	E(2)	Young's modulus in layer 2

Notes	Columns	Variables	Entry
	31-40	V(2)	Poisson's ratio in layer 2
	:	:	:
		E(NLA)	:
		V(NLA)	:

g. Item 7: Subgrade Layer Thickness Card (8F10.2).

Note: Skip Item 7 if NLA = 1 .

Notes	Columns	Variables	Entry
	1-10	HI(1)	Thickness of the first layer
	11-20	HI(2)	Thickness of the second layer
		:	:
		HI(NN)	Thickness of the last layer, where NN = NLA

h. Item 8: Nodal Points Coordinates Cards (8F10.5).

Card	1:	X-coordinates
caru	1.6	v-coolainares

Notes	Columns	Variables	Entry
(1)	1-10	X(1,1)	X-coordinate of the first node of slab 1
	11-20	X(1,2)	X-coordinate of the second node of slab 1
		:	:
		X(1,NX1)	X-coordinate of the NX1 node of slab 1
(2)		X(2,1)	X-coordinate of the first node of slab 2
		X(2,2)	X-coordinate of the second node of slab 2
		:	:
		X(2,NX2)	X-coordinate of the NX2 node of slab 2
Card 2:	Y-coordina	tes	
Notes	Columns	Variables	Entry
	1-10	Y(1)	Y-coordinate of the first node

Notes	Columns	Variables	Entry
	11-20	Y(2)	Y-coordinate of the second node
		:	:
		Y(NY)	Y-coordinate of the NY node

NOTES:

- (1) The nodes at both sides of the joint should be identical; i.e., if the slab length is 180 in. and 12 nodes are used in the X-direction, the coordinates of X(y,12) and X(2,1) are both 180.
- (2) Skip input for slab 2 if NSLAB = 1.

When temperature is considered, the dimensions of two slabs have to be identified. Otherwise, erroneous results will be computed.

i. Item 9: Subgrade Contact Card (1615).

Note: Skip Item 9 if NOTCON = 0; i.e., the slabs are initially in full contact with the subgrade.

Notes	Columns	<u>Variables</u>	Entry
(1)		NZ(I)	Nodal number at which reactive pressure is initially assumed zero

NOTES:

(1) Continue the input until the number of NOTCON is satisfied. Continue to next data card if NOTCON is greater than 16.

j. Item 10: Data Card (615).

Notes	Columns	Variables	Entry
	1-5	NGAP	Total number of nodes at which a gap exists be- tween slab and subgrade; assign 0 if no gap exists
	6-10	NTEMP	Condition of temperature warping:
			EQ.0 Temperature gra- dient is zero
			EQ.1 Temperature gra- dient is not zero
	11-15	NLOAD	Number of elements on which load is applied; use 0 if there is no load

Notes	Columns	Variables	Entry
(1)	16-20	NMCF	Number of concentrated nodal forces and moments that are to be read in; assign 0 if no moments or forces are applied
(2)	21-25	ICL	Maximum number of iterations allowed for coarse control; generally use 49 or more
(2)	26-30	ICLF	Maximum number of iterations allowed for fine control; generally use 199 or more
(3)	31-35	NCK	Total number of nodal points for checking convergence
	36-40	NWT	Weight of slab consideration:
			EQ.0 Weight is not considered
			EQ.1 Weight is con- sidered
(4)	41-45	IGNOR	A parameter indicating whether the reduction of relaxation factor RFJ should be ignored:
			EQ.O If RFJ is reduced
NORTH			EQ.1 If RFJ is not re- duced whenever the results diverge

NOTES:

- (1) The concentrated force is considered to be positive if it is acting downward and to be negative if it is acting upward. Positive moment follows the right-hand screw system, as shown in Figure 1 of Report 1 of this series. The program is dimensioned for 50 concentrated forces and moments. If NMCF is greater than 50, dimensions of NFF, NFI, and NF must be increased.
- (2) See note 1 of Item 11. Coarse and fine controls are used before and after the subgrade contact condition is determined. For a given contact condition, coarse control is used to chuck the deflection criterion. Once the subgrade contact condition is finally determined, fine control

is used to obtain accurate solutions. In the case where NCYCLE = 1, coarse control is still used prior to the use of fine control. Note ICLF should always be greater than ICL .

In some problems, ICLF may be exhausted before the criterion DELF is satisfied. Before rejecting the solution, it may be wise to check to see how far the solution is from satisfying the criterion. For instance, if DELF = 0.001 and computed convergence is 0.002 or 0.0025 and the computed results seem to be reasonable, the solution may be considered acceptable. In some problems, it may be very hard to satisfy the specified convergence criterion.

- (3) Two or three points should suffice. They should be selected under or near the load where stresses and deflections are the greatest. When NSLAB = 2, the convergence points should be selected along the joint.
- (4) The use of IGNOR is to increase the flexibility of the program. In some cases, it may be desirable to check the convergence condition when the relaxation factor is fixed at a certain value. It was found that in some cases the computed results are better when the problem is computed with a constant RFJ of 0.5 than when computed with either a smaller constant RFJ or a varying RFJ (reducing automatically). For instance, if the loads are symmetrically placed on the slab, the stresses should be symmetrical at corresponding points. It was found that the magnitudes of the stresses computed at the corresponding points were much closer when computed with a constant RFJ of 0.5 than when computed otherwise. It is thus recommended to use RFJ = 0.5 or 0.1 and IGNOR = 1 in the computation if the solution can be obtained. The use of an RFJ that is too small can artificially accelerate the convergence, but the results obtained may be erroneous.

k. Item 11: Data Card (8F10.5).

Notes	Columns	Variables	En	try
	1-10	TEMP	Difference i ture, in deg heit,* betwe bottom of sl	rees Fahren- en top and
			EQ.positive	slab curled upward
			EQ.negative	slab curled downward

^{*} A table of factors for converting U.S. customary units of measurement to metric (SI) units is presented on page 3.

Notes	Columns	Variables	Entry
	11-20	ବ	Uniformly applied pres- sure in psi
(1)	2130	DEL	Tolerance of convergence for coarse control; usually use 0.01
(1)	31-40	DELF	Tolerance of convergence for fine control; usu-ally use 0.001
(2)	41-50	RFJ	Initial relaxation factor at the joint; generally use 0.5 or 0.1
(3)	51-60	EFF	Efficiency of shear transfer across the joint. It ranges from 1 to 0

NOTES:

- (1) DEL and DELF correspond to ICL and ICLF in Item 10, respectively.
- (2) The use of RFJ is to reduce the deflections transferred from one slab to the other. The program reduces the value of RFJ automatically when the solution diverges. When dowel bars are used, it was found that the solution can be obtained only when RFJ is reduced to 0.01. When dowel bars are not used, however, an erroneous solution was obtained when RFJ was set to 0.01.
- (3) The value of efficiency across the joint varies from 0 to 1. If LTR (input in Item 3) is equal to 1, EFF must be input as 1. However, it does not mean that 100 percent shear transfer is used in the program.

No minimum value of RFJ is used in the program. However, a value too small would result in a shear transfer across the joint that is too small during each iteration, and consequently the computed results could be erroneous because the convergence of the solution is "artifically" enforced.

When the pavement geometry and loading conditions in the pavement are such that the computed results at corresponding locations in two slabs are supposed to be symmetrical, joint efficiency other than 100 percent should not be used. Otherwise, erroneous results will be computed.

1. Item 12: Concentrated Forces and Moments Card [4(15, 15, F10.2)].

Note: Skip Item 22 if NMCF = 0 .

Notes	Columns	Variables	Entry
	1-5	NF(I)	Nodal number at which concentrated forces or moments are specified
(1)	6-10	NFF(I)	Nature of specified force at node I
(2)	11-20	FO[NF(I)-1] × 3 + NFF(I)	Concentrated force or moment at node I

NOTES:

- (1) NFF(I) = 1 for vertical force, 2 for moment about X-axis, and 3 for moment about Y-axis.
- (2) The magnitude of concentrated force or moment at each node input in the equation number is related to nodal number I by NF(I) 1 \times 3 + NFF(I). For instance, if a moment about Y-axis is applied at node 13, the equation number will be $(13-1)\times 3+3=39$. Note that the nodes are numbered consecutively from bottom to top and then from left to right beginning from the first slab and ending at the last slab.

m. Item 13: Check Convergence Card (1615).

Notes	Columns	Variables	Entry
	1-5	NODCK(1)	Nodal number of the first node at which the conver- gence is checked
	€ - 10	NODCK(2)	Nodal number of the sec- ond node at which the convergence is checked
		:	
		:	
		NODC(NCK)	Nodal number of the NCK node at which the con- vergence is checked

n. Item 14: Dowel Bar Information Card (5F10.5, E10.3).

Note: Skip Item 14 if LTR = 0.

Notes	Columns	<u>Variables</u>	Entry
	1-10	BD	Bar diameter
	11-20	BS	Bar spacing
	21-30	WJ	Joint opening
	31-40	PRSB	Poisson's ratio of the bar

Notes	Columns	Variables	Entry
	41-50	YMSB	Young's modulus of the bar
	51-60	DSM	Modulus of dowel support

o. Item 15: Gaps Read In Cards.

Note: Skip Item 15 if NGAP = 0.

Card 1: Nodal Points (1615)

Notes	Columns	Variables	Entry
	1-5	NG(1)	Nodal number of the first node at which a gap exists
	6-10	NG(2)	Nodal number of the sec- ond node at which a gap exists
		:	
		NG(NGAP)	Nodal number of the NGAP node at which a gap exists

Card 2: Gaps (8F10.5)

Notes	Columns	Variables	Entry
	1-10	CURL(NG(1))	Amount of gap at node NG(1)
	11-20	CURL(NG(2))	Amount of gap at node NG(2)

.

CURL(NG(NGAP)) Amount of gap at node NG(NGAP)

p. Item 16: Total Uniformly Applied Load Card (F12.2).

Note: Skip Item 16 if NLOAD = 0 .

Notes	Columns	Variables	Entry
(1)	1-12	RLOAD	Total uniformly applied load on the slab

NOTES:

(1) The total load refers to the uniformly applied load only. The total load should be divided by 2 or 4 if it is symmetric with respect to one axis (X- or Y-axis) or both the X- and the Y-axis, respectively. Additional point loads applied at nodal points are excluded.

q. Item 17: Loading Cards.

Note: Skip Item 17 if NLOAD = 0 .

Card 1: Loading Elements (1615)

Notes	Columns	Variables	Entry
(1)	1-10	NL(1)	Element number of the first element over which load is applied
(1)	11-20	NT(5)	Element number of the second element over which load is applied
		:	:
		NL(NLOAD)	Element number of the last element over which load is applied

NOTES:

(1) Beginning from the first slab and ending at the last slab, the nodes and elements are numbered consecutively from bottom to top and then from left to right.

Card 2: Load Magnitude (4F10.5)

Notes	Columns	<u>Variables</u>	Entry
(1)	1-10	XDA(I,1)	Lower limit of loaded area in element I in X-direction
(1)	11-20	XDA(I,2)	Upper limit of loaded area in element I in X-direction
(2)	21-30	YDA(I,1)	Lower limit of loaded area in element I in Y-direction
(2)	31-40	YDA(I,2)	Upper limit of loaded area in element I in Y-direction

NOTES:

- (1) Use -1 to +1 if the load covers the whole length of the element.
- (2) Use -1 to +1 if the load covers the whole width of the element.

r. Item 18: Subgrade Stresses Card.

Note: Skip Item 18 if NCONF = 0 .

Card	1:	Number	of	Computations	(2110)	

Notes	Columns	Variables	Entry
	1-10	NZZ	Number of depths to be computed
	11-20	NR	Number of offsets at each depth to be computed
Card 2:	Depth Card	(8F10.5)	
Notes	Columns	Variables	Entry
	1-10	ZZ(1)	Depth of first computation
	11-20	ZZ(2)	Depth of second computation
		ZZ(NZ)	Depth of the last computation
Card 3:	Offset Car	i (8F10.5)	
Notes	Columns	<u>Variables</u>	Entry
(1)	-1-10	XR(1)	X-coordinate of first computation
	11-20	YR(l)	Y-coordinate of first computation
	21-30	XR(2)	X-coordinate of second computation
	31-40	YR(2)	Y-coordinate of second computation
		XR(NR)	X-coordinate of last computation
		YR(NR)	Y-coordinate of last computation

NOTES:

(1) Computations at each offset point are made at all the high depths. The origin of the coordinates is at nodal point 1; i.e., model of slab 1. Refer to the nodal numbers shown in Figure 2 of Report 2 if stresses and deflections are to be computed. The first location is directly under node 1, the second location is midpoint between nodes 5

and 8, and the third location is at the center of element 13. The input values of XR(1), YR(1), XR(2), YR(2), XR(3), and YR(3) should then be 0, 0, 135, 90, -135, and -135. Note that nodes 1, 16, 21, and 36 share the same location.

PART V: EXAMPLE PROBLEMS

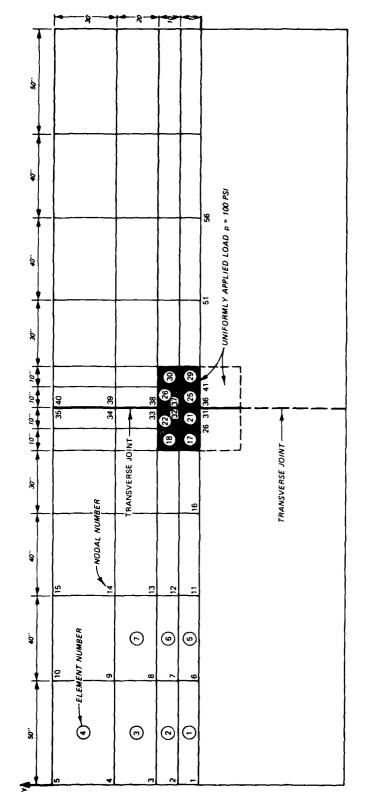
34. In this Part, the input data of four example problems are presented. Printouts of the computer outputs for the example problems are also presented and explained.

Example Problem 1: A Two-Slab Pavement System on Elastic Solids

- 35. Figure 2 shows the finite element grid of a two-slab pavement. The nodes and elements are numbered consecutively from bottom to top and then from left to right. The input data consist of the following information:
 - a. The concrete slab is 8 in. thick with a Young's modulus of 4,000,000 psi and a Poisson's ratio of 0.15. The elastic subgrade soil has a Young's modulus of 10,000 psi and a Poisson's ratio of 0.4.
 - <u>b</u>. The pavement is subjected to a uniformly distributed square load applied at the center of the slabs. The option of symmetry with respect to the X-axis is used.
 - c. Dowel bars are not used in the transverse joint connecting the two slabs. The joint is assumed to have a certain percentage of efficiency in shear transfer across the joint.
 - d. The input data for Example problem 1 are given in Table 2. The joint efficiency in this particular case is 100 percent; i.e., the deflections at both sides of the joint are equal.
- 36. Table 3 shows the printout of the computer output for Example problem 1. The printout is in many places self-explanatory. For convenience of explanation, entry numbers are used where explanations are needed.

Entry 1

37. Because the option of symmetry with respect to the X-axis was used, the parameter NSYM was input as 3. Because the option of shear transfer across the joint is used, the parameter LTR was input as 0. The half bandwidth NB = 21 was the minimum required. In this



Finite element layout and loading conditions for Example problem 1 Figure 2.

Example Problem 1, Input Data for a Two-Slab Pavement on an Elastic Solid, 100 Percent Shear Transfer Across the Joint Table 2.

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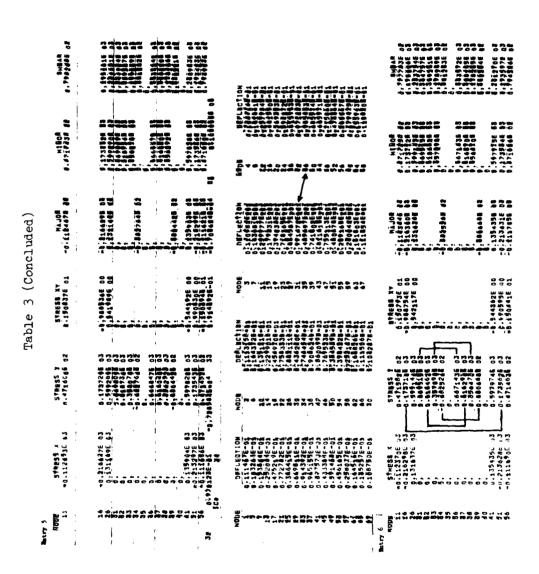
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(Sheet 3 of 3)



special case, the relaxation factor RFJ = 0.1 is fixed as a constant by setting the parameter IGNOR = 1.

Entry 2

38. The initial curling and gap at all nodes are 0 because the temperature and the gap are not considered in the computation.

Entry 3

39. Since NCYCLE = 1 , i.e., the slab is assumed to be in contact with the subgrade all the time, NIC will not be iterated greater than 1.

Entry 4

40. The deflections at each node are tabulated whether convergence requirements are met. Positive deflection indicates downward movement.

Entry 5

41. The stress components at preselected points are printed. Positive stress indicates that the slab has compression at the top and tension at the bottom and negative stress indicates compression at the bottom and tension at the top. The symbols of STRESS XY, MAJOR, MINRO, and SHEAR stand for shear stress, major principal stress, minor principal stress, and maximum shear stress, respectively.

Entry 6

- 42. The stresses and displacements are computed for one more iteration for inspection of convergence by the user. When the solution correctly converges, the differences in the computed results between two iterations should be very insignificant. Otherwise, the solution is not convergent.
- 43. Because of the existence of symmetry with respect to the Y-axis along the transverse joint, the stresses and deflections at corresponding points in the left and right sides should be equal. Printed results in Entry 6 show that the stresses and deflections at nodal points 11, 16, 26, 31, 32, 33, 34, and 35 are very close to those computed in points 56, 51, 41, 36, 37, 38, 39, and 40, respectively.
- $^{1\!\!14}$. The following two special features in Example problem 1 should be pointed out:

- a. Because the slabs are symmetrically loaded, the use of a shear transfer across the joint less than 100 percent will produce meaningless results.
- b. While the system is symmetrically loaded, the use of the symmetry option with respect to both the X- and Y-axis is wrong because the axis of symmetry in the Y-direction lies on the joint which is formidable.
- 45. The results shown in Table 3 were computed with the relaxation factor RFJ = 0.1.
- 46. Table 4 is another printout of the computer output with the same conditions as those shown in Example problem 1, except that the efficiency of shear transfer across the joint is assumed to be 80 percent and the loads applied at the right slab are removed. Eighty percent shear transfer denotes that the deflections at the unloaded (or less heavily loaded) slab are 80 percent of the loaded (or more heavily loaded) slabs. The computed deflections at nodes 31 and 36 indicate that the computed results are correct. It should be noted that since 80 percent shear transfer is assumed, meaningless results will be computed if the slabs are symmetrically loaded with respect to the transverse joint.

Example Problem 2: A Two-Slab Pavement System on Elastic Solids, Dowel Bars Across the Joint

47. The same configuration of pavements used in Example probmen 1 (Figure 2) is used in this one. Dowel bars are used across the transverse joint; the bars have a diameter of 1 in. and are placed 12 in. apart. The input data and the printout of the computer output are given in Tables 5 and 6, respectively. When dowel bars are used, the options LTR and EFF are both input as 1. The computed results show that the stress σ_y and deflections in the loaded slab are greater than those in the unloaded slab.

Example Problem 3: A Two-Slab Pavement System on Layered Elastic Solids

48. Table 7 shows the input data for a two-slab pavement system

(Sheet 1 of 3)

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Table 4. Computer Output for Example Problem 1, Elastic Solid and 80 Percent Shear Transfer Across the Joint, One Loaded Slab

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Example Problem 2, Input Data for a Two-Slab Pavement on an Elastic Solid, 1-in. Dowel Bars Across the Joint Table 5.

GENERAL PURPOSE DATA FORM

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Table 6. Computer Output for Example Problem 2, Elastic Half-Space and 1-in. Dowel Bars Across the Joint

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Table 7. Example Problem 3, Input Data for a Two-Slab Pavement on Three-Layer Elastic Solid, 100 Percent Shear Transfer

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Printout of the Computer Output for Example Problem 3,
Three-Layer Elastic Subgrade, 100 Percent Shear
Transfer Across the Joint

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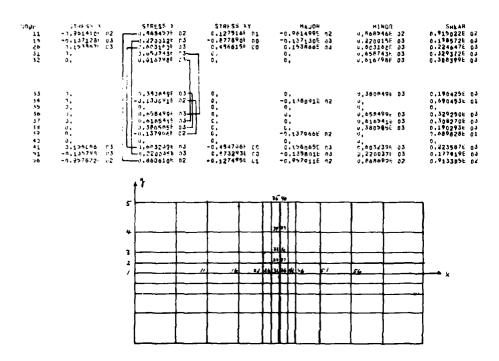
(Sheet 1 of 3)

Table 8 (Continued)

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(Sheet 2 of 3)

Table 8 (Concluded)



(Sheet 3 of 3)

resting on a three-layer linear elastic subgrade. One hundred percent joint efficiency is assumed. The finite element grid pattern is the same as shown in Figure 2.

49. Table 8 shows the printout of the computer output for Example problem 3. The layered subgrade information indicates that the elastic moduli of the three-layer subgrade are 60,000, 30,000, and 10,000 psi and that the Poisson's ratio in each layer is 0.4. Because of the assumption of 100 percent shear transfer across the joint and the symmetrical loading, the stresses and deflections at corresponding nodes across the joint are nearly identical.

Example Problem 4: A Four-Slab Pavement System on Elastic Solids, Symmetrically Loaded, with 100 Percent Shear Transfer Across the Joint

50. Figure 3 shows the finite element layout for a four-slab pavement system with the load applied symmetrically at the pavement's center. This is the only option for the analysis of a four-slab pavement system by use of the WESLAYER program. Although it is a four-slab system, the program analyzes only one-quarter of the system, i.e., one slab. Consequently, 100 percent joint efficiency should be assumed

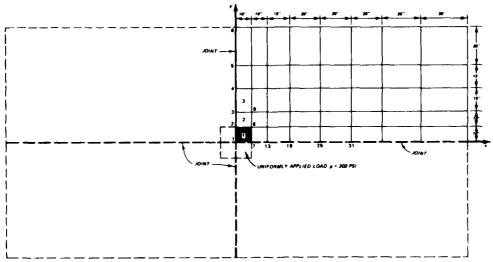


Figure 3. Finite element layout for Example problem 4, symmetrically loaded four-slab system

for the problem. The coordinates and loading condition input into the program are shown in Figure 3.

- 51. The input data for this problem are given in Table 9. It should be pointed out that the parameter NSYM is input as 5 for a four-slab system. The number of slab NSLAB is input as 1, instead of 4, because there is only one slab involved in the computation. (In the case for a single slab symmetrically loaded, NSYM should be input as 4.)
- 52. The printout of the computer output for Example problem 4 is presented in Table 10. The printout is self-explanatory. Because of symmetry, the computed stresses and deflections at nodal points 2, 3, 4, and 5 should be very close to those computed at nodes 7, 13, 19, and 25, respectively. The computed results show that it is true only at nodal points 2 and 7. At nodes closer to the free edge of the pavement, the discrepancy becomes greater. This is believed to be caused by the fact that the slabs have different dimensions in the X- and Y-directions. It is also to be noted that at nodes 1 and 6, i.e., nodes at the corners of the slabs, the stresses vanish.

Table 9. Example Problem 4, Input Data for a Four-Slab Pavement on an Elastic Solid, Symmetrically Loaded on Both X- and Y-Axes, 100 Percent Shear Transfer Across the Joints

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Table 10. Printout of Computer Output for Example Problem 4, a Four-Slab Pavement System on Elastic Solids, 100 Percent Shear Transfer Across the Joint

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PART VI: CONCLUSIONS AND RECOMMENDATIONS

53. The computer program WESLAYER has the capability of obtaining solutions for rigid multicomponent pavements with discontinuities. The foundation soil can be either elastic solid or layered elastic solid. Because of the length of computer time required and the limitation of two slabs, it is recommended that the program be used for research and analysis purposes.

In accordance with letter from DAEN-RDC, DAEN-ASI dated 22 July 1977, Subject: Facsimile Catalog Cards for Laboratory Technical Publications, a facsimile catalog card in Library of Congress MARC format is reproduced below.

Chou, Yu T.

Structural analysis computer programs for rigid multicomponent pavement structures with discontinuities--WESLIQID AND WESLAYER: Report 3: Manual for the WESLAYER Finite Element Program / by Yu T. Chou (Geotechnical Laboratory, U.S. Army Engineer Waterways Experiment Station.) -- Vicksburg, Miss.: The Station, [1981.]

64 p.: ill.; 27 cm. -- (Technical report / U.S. Army Engineer Waterways Experiment Station; GL-81-6, Report 3.)

Cover title. "May 1981."

"Prepared for Office, Chief of Engineers, U.S. Army, under Project No. 4A762719AT40, Work Units 001 and 003."
"Available from National Technical Information Service, Springfield, Va. 22161."

Chou, Yu T.
Structural analysis computer programs for rigid: ... 1981.
(Card 2)

1. Computer programs. 2. Finite element method.
3. Pavements. 4. WESLAYER (Computer program.)
5. WESLIQID (Computer program.) I. United States.
Army. Corps of Engineers. Office of the Chief of Engineers. II. United States. Army Engineer Waterways Experiment Station. Geotechnical Laboratory. III. Title IV. Series: Technical report (United States. Army Engineer Waterways Experiment Station); GL-81-6, Report 3.
TA7.W34 no.GL-81-6 Report 3